

Introduction



Today

- Welcome to OS
- Administrivia
- OS overview and history
- Computer system overview

Next time

- OS components & structure

Why study operating systems?

- **Tangible reasons**

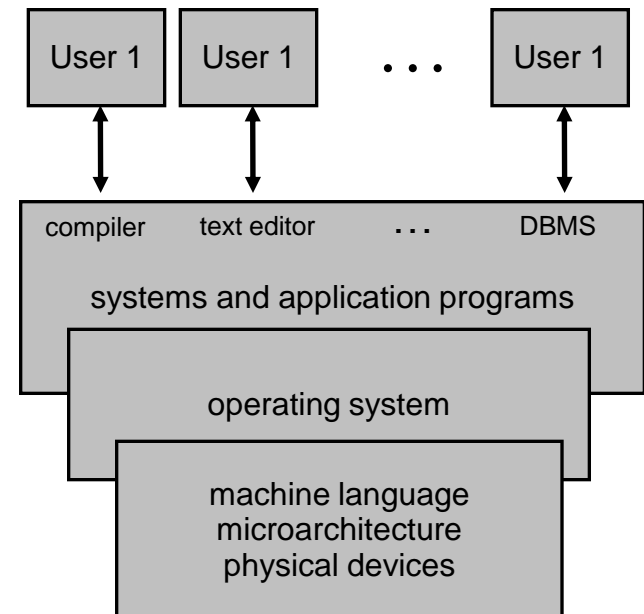
- Build/modify one - OSs are everywhere
- Administer and use them well
- Tune your favorite application performance
- Great capstone course

- **Intangible reasons**

- Curiosity
- Use/gain knowledge from other areas
- Challenge of designing large, complex systems

A computer system - Where's the OS?

- Hardware provides basic computing resources
- Applications define ways in which resources are used to solve users' problems
- *OS controls & coordinates use of hardware by users' applications*
- A few vantage points
 - End user
 - Programmer
 - OS Designer



What is an operating system?

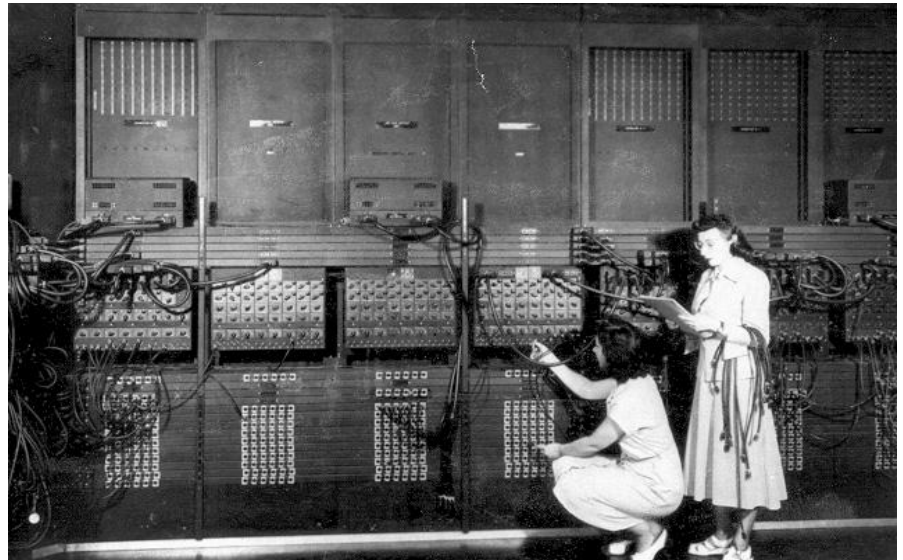
- Extended machine – top-down/user-view
 - Hiding the messy details, presenting a virtual machine that's easier to program than the HW
- Resource manager – bottom-up/system-view
 - Everybody gets a fair-share of time/space from a resource (multiplexing in space/time)
 - A control program – to prevent errors & improper use (CP/M?)
- A bundle of helpful, commonly used things
- Goals
 - Convenience – make solving user problems easier
 - Efficiency – use hardware in an efficient manner (\$\$\$ machines demand efficient use)

What's part of the OS?

- Trickier than you think: file system, device drivers, shells, window systems, browser, ...
- Everything a vendor ships with your order?
- The one program running at all times, or running in kernel mode
 - Everything else is either a system program (ships with the OS) or an application program
 - *Can the user change it?*
- *Why does it matter? In 1998 the US Department of Justice filed suit against MS claiming its OS was too big*

The evolution of operating systems

- A brief history & a framework to introduce OS principles
- Early attempts – Babbage's (1702-1871)
 - Analytical Engine (Ada Lovelace – World's first programmer)
- 1945-55 – Vacuum tubes and plugboards
 - ABC, MARK 1, ENIAC
 - No programming languages, no OS
 - A big problem
 - Scheduling – signup sheet on the wall



Evolution ... Batch systems (1955)

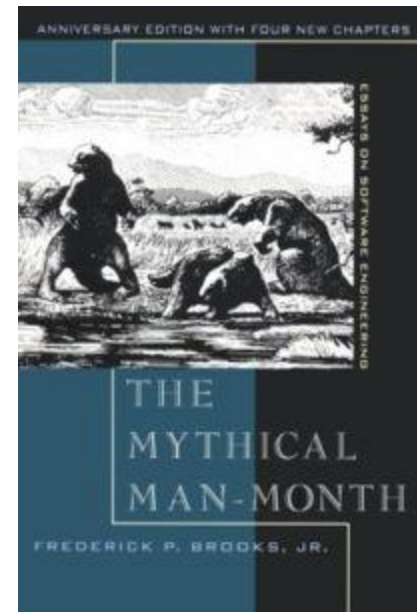
- Transistors → machs. reliable enough to sell
 - Separation of builders & programmers
- Getting your program to run
 - Write it in paper (maybe in FORTRAN)
 - Punch it on cards & drop cards in input room
 - Operator may have to mount/dismount tapes, setting up card decks, ... setup time!
- Batch systems
 - Collect a tray of full jobs, read them all into tape with a cheap computer
 - Bring them to the main computer where the “OS” will go over each jobs one at a time
 - Print output offline

Evolution ... Spooling (1965)

- Disks much faster than card readers & printers
- Spool (Simultaneous Peripheral Operations On-Line)
 - While one job is executing, spool next one from card reader onto disk
 - Slow card reader I/O overlapped with CPU
 - Can even spool multiple programs onto disk
 - OS must choose which one to run next (job sched)
 - But CPU still idle when program interact with a peripheral during execution
 - Buffering, double buffering

Evolution ... Multiprogramming (1965)

- To increase system utilization
 - Keeps multiple runnable jobs loaded in memory at once
 - Overlap I/O of a job with computing of another
 - Needs asynchronous I/O devices
 - Some way to know when devices are done
 - Interrupt or polling
 - Goal- optimize system throughput
 - Cost on response time
- IBM OS/360 & the tar pit



Evolution ... Timesharing (1965)

- To support interactive use
 - Multiple terminals into one machine
 - Each user has the illusion of owning the entire machine
- Time-slicing
 - Dividing CPU equally among users
 - If jobs are truly interactive, CPU can jump between them without users noticing it
 - Recovers interactivity for the user (why do you care?)
- CTSS (Compatible Time Sharing System), MULTICS and UNIX

Evolution ... PCs (1980)

- Large-scale integration >> small & cheap machines
- 1974 – Intel's 8080 & Gary Kildall's CP/M
- Early 1980s – IBM PC, BASIC, CP/M & MS-DOS
- User interfaces, XEROX Altos, MACs and Windows



Xerox Alto 1973

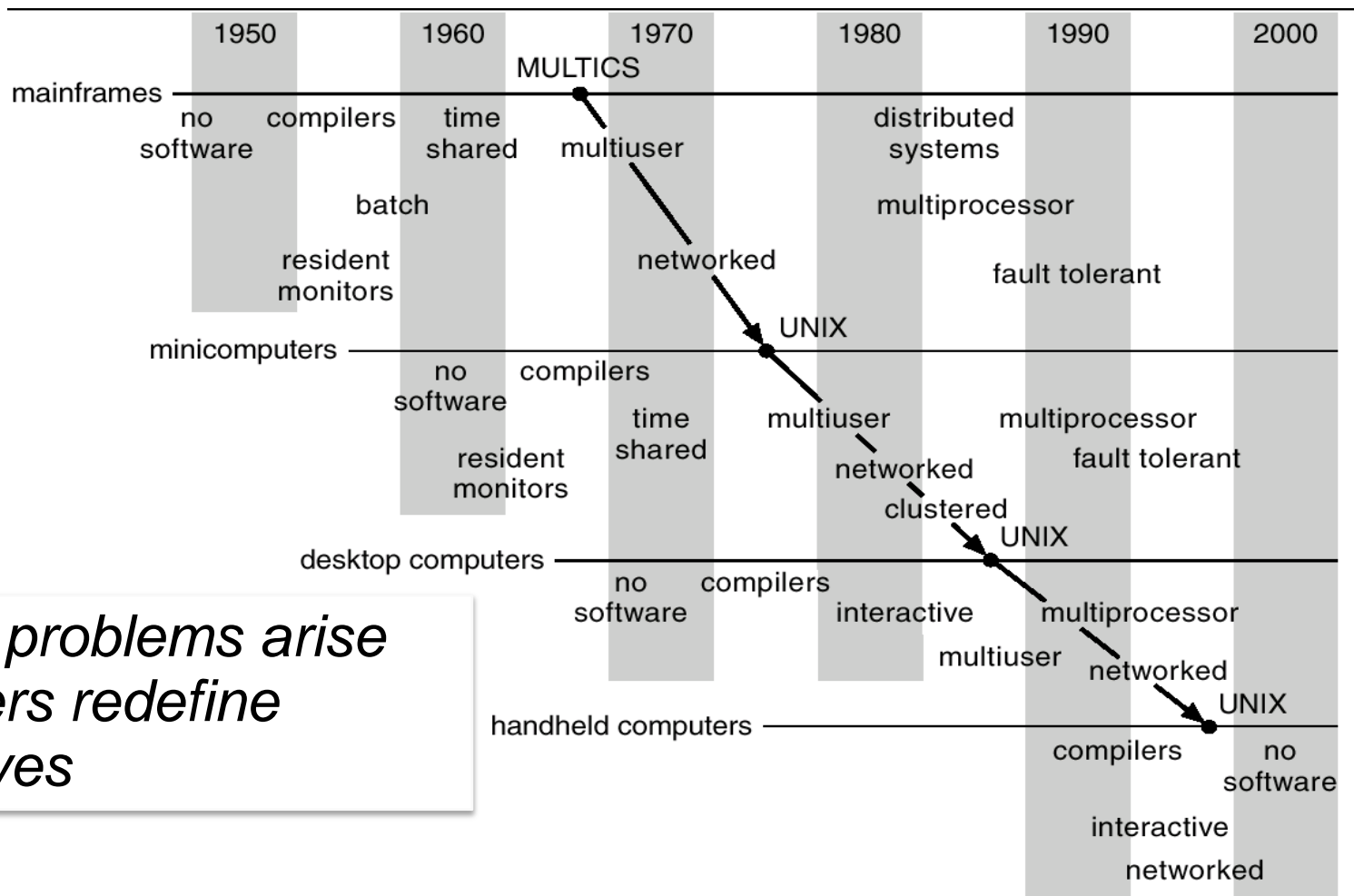
IBM PC circa 1981



Evolution ... Distributed & pervasive

- Facilitate use of geographically distributed resources
 - Workstations on a LAN or across the Internet
- Support communication between programs
- Speed up is not really the issue, but access to resources
- Architectures
 - Client/servers
 - Mail server, print server, web server
 - Peer-to-peer
 - (Most) everybody is both, server and client
- Pervasive computing & embedded devices

"Ontogeny recapitulates phylogeny"*



But new problems arise and others redefine themselves

The development of an embryo repeats the evolution of the species (* Ernst Haeckel)

Course overview ...

● Overall structure

- Lectures
- TA Sessions
 - Once a week and focused on projects
- Homework (5)
 - Look at them as reading enforcers

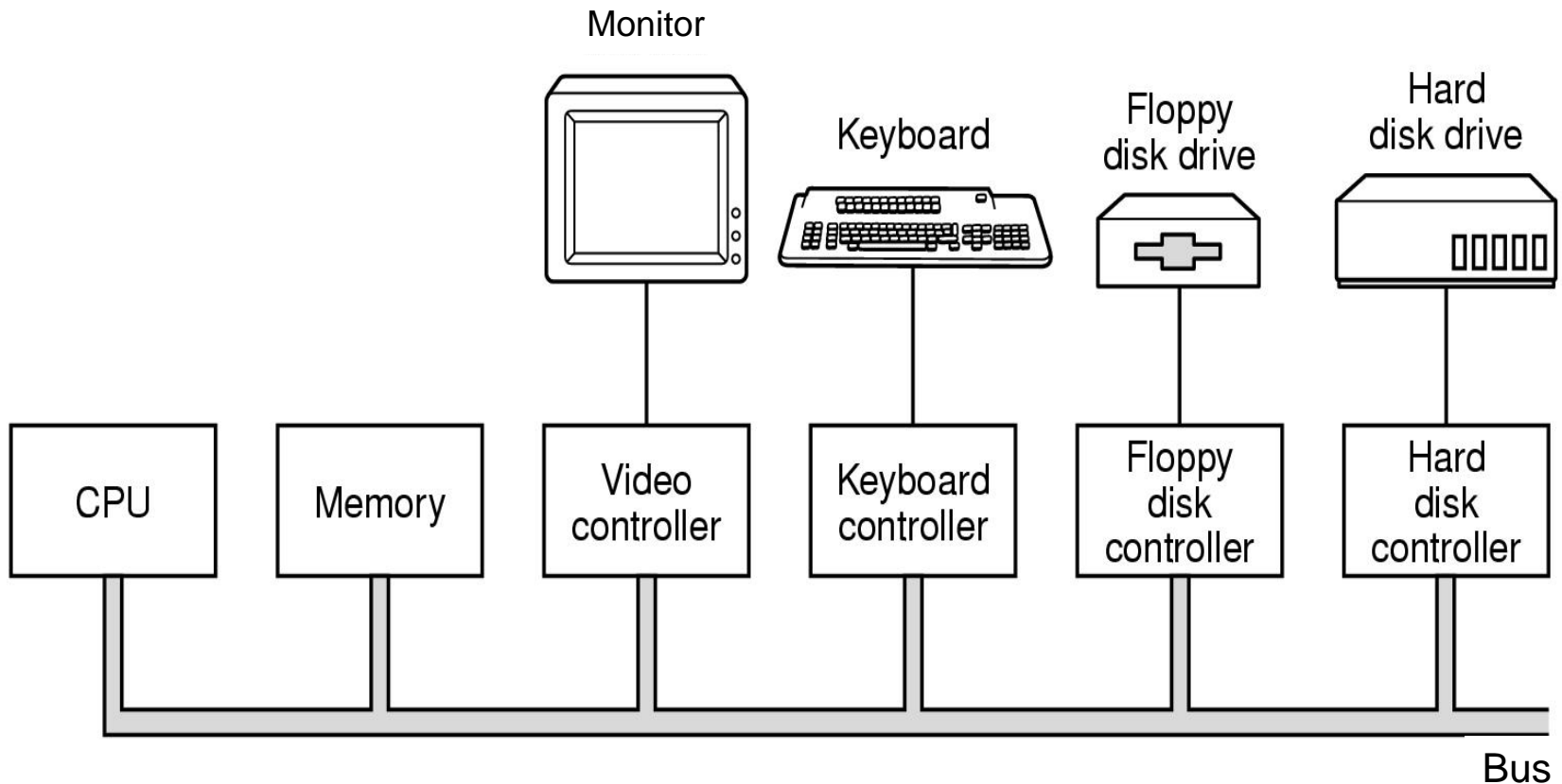
1: Introduction to Operating Systems	09/25	10/02
2: Processes and Threads	10/16	10/23
3: Memory Management and Virtual Memory	11/06	11/13
4: I/O and File Systems	11/20	12/02
5: Research in Operating Systems	12/04	12/04 (<i>in-class</i>)

Course overview

- Overall structure
 - ...
 - Projects (4)
 - ***First one out next Tuesday!***
 - Exams (2)
- Course book & other material
 - Read before class
- Other recommended sources
 - Stevens' book
- Grading, policies

Computer systems structure

- Abstract model of a simple computer



Processor

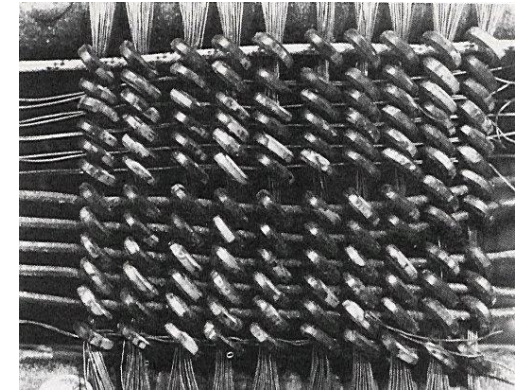
- Basic operation cycle
 - Fetch next instruction
 - Decode it to determine type & operands
 - Execute it
- Set of instructions
 - Architecture specific - Pentium != SPARC
 - Includes: combine operands (ADD), control flow, data movement, etc
- Since memory access is slow ... registers
 - General registers to hold variables & temp. results
 - Special registers: Program Counter (PC), Stack Pointer (SP), Program Status Word (PSW)
- Moving away from basic operation cycle: pipeline architectures, superscalar, ...



Memory

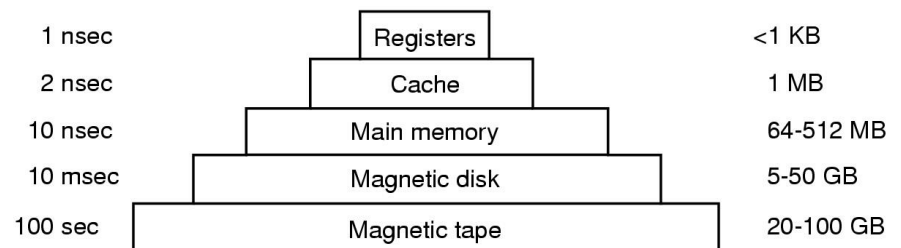
- Ideally – fast, large & cheap
- Reality – storage hierarchy
 - Registers
 - Internal to the CPU & just as fast
 - 32x32 in a 32 bit machine
 - Cache
 - Split into cache lines
 - If word needs is in cache, get in ~2 cycles
 - Main memory
 - Hard disk
 - Magnetic tape
 - Coherency?

First core-based memory: IBM 405 Alphabetical Accounting Machine



Typical access time

Typical capacity



OS protection

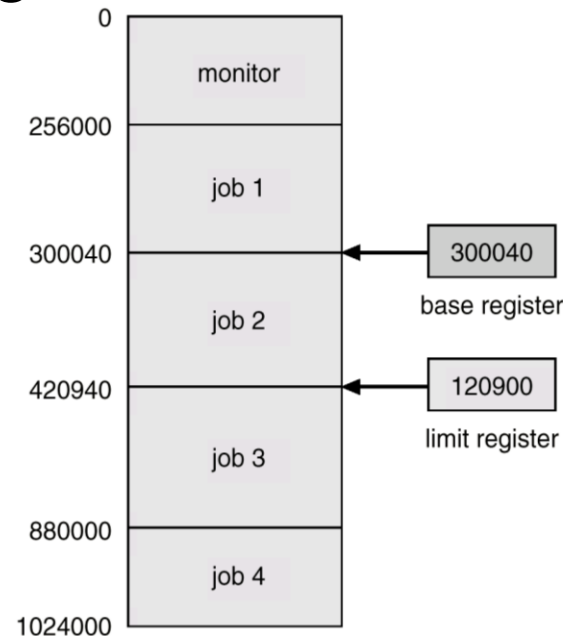
- Multiprogramming & timesharing are useful but
 - How to protect programs from each other & kernel from all?
 - How to handle relocation?
- Some instructions are restricted to the OS
 - e.g. Directly access I/O devices
 - e.g. Manipulate memory state management
- How does the CPU know if a protected instructions should be executed?
 - Architecture must support 2+ mode of operation
 - Mode is set by status bit in a protected register (PSW)
 - User programs execute in user mode, OS in kernel mode
- Protected instructions can only be executed in kernel mode

Crossing protection boundaries

- How can apps. do something privileged?
 - e.g. how do you write to disk if you can't do I/O?
- User programs must call an OS procedure
 - OS defines a sequence of system calls
 - How does the user to kernel-mode transition happen?
- There must be a system call instruction, which
 - Causes an exception (throws a soft interrupt) which vector to a kernel handler
 - Passes a parameter indicating which syscall is
 - Saves caller's state so it can be restored
 - OS must verify caller's parameters
 - Must be a way to go back to user once done

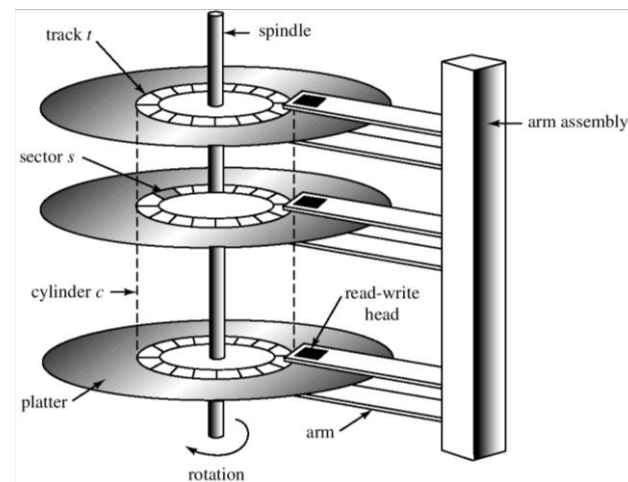
Memory relocation

- Relocation simplest solution
 - Base (start) of program + limit registers
 - Solves both problems; cost 2 registers + cycle time incr
- Check and mapping to virtual address done by MMU (memory management unit)
- More sophisticated alternatives
 - 2 base and 2 limit registers for text & data; allow sharing program text
 - Paging, segmentation, virtual memory



I/O devices: magnetic disks

- 1+ platters rotating at $>5,400$ RPM
- Mechanical arm (arm assembly)
- Platter logically divided in tracks, sectors
- Cylinder – track for a given head position
- Moving & transfer times
 - To next cylinder ~ 1 msec
 - To random cylinder $\sim 5-10$ msec
 - For sector to get under $\sim 5-10$ msec
 - Transfer once in the right place $5-160$ MB/sec



I/O devices

- I/O Device
 - Device + Controller (simpler I/F to OS; think SCSI)
 - Read sector x from disk y → (disk, cylinder, sector, head), ...
- Device driver – SW to talk to controller
 - To use it, must be part of kernel: ways to include it
 - Re-link kernel with new driver and reboot (UNIX)
 - Make an entry in an OS file & reboot (OS finds it at boot time and loads it)
 - Dynamic load – OS takes new driver while running & installs it
- I/O can be done in 3 different ways
 - Busy waiting/synchronous
 - Interrupt-based/asynchronous
 - Direct Memory Access (DMA)

OS control flow

- OSs are event driven
 - Once booted, all entry to kernel happens as result of an event (e.g. signal by an interrupt), which
 - Immediately stops current execution
 - Changes to kernel mode, event handler is called
- Kernel defines handlers for each event type
 - Specific types are defined by the architecture
 - e.g. timer event, I/O interrupt, system call trap
- Handling the interrupt
 - Push PC & PSW onto stack and switch to kernel mode
 - Device # is index in interrupt vector - get handler
 - Interrupt handler
 - Stores stack data
 - Handles interrupt
 - Returns to user program after restoring program state

Interrupts and exceptions

- Three main types of events: interrupts & exceptions
 - Exceptions/traps caused by SW executing instructions
 - e.g., the x86 'int' instruction
 - e.g., a page fault, or an attempted write to a read-only page
 - An expected exception is a "trap", unexpected is a "fault"
 - Interrupts caused by HW devices
 - e.g., device finishes I/O, timer fires

Timers

- How can the OS prevent runaway user programs from hogging the CPU (infinite loops?)
 - Use a hardware timer that generates a periodic interrupt
 - Before it transfers to a user program, the OS loads the timer with a time to interrupt
 - When time's up, interrupt transfers control back to OS
 - OS decides which program to schedule next
 - Interesting policy question: 1+ class scheduled for that
- Should the timer be privileged?
 - for reading or for writing?

Synchronization

- Issues with interrupts

- May occur any time, causing code to execute that interferes with the interrupted code
- OS must be able to synchronize concurrent processes

- Synchronization

- Guarantee that short instruction sequences (e.g. read-modify-write) execute atomically
- Two methods
 - Turn off interrupts, execute sequence, reenables interrupts
 - Have special, complex atomic instructions – test-and-set

Management of concurrency & asynchronous events is the biggest difference bet/ systems-level & traditional application programming.

Summary

- In this class you will learn

- Major components of an OS
- How are they structured
- The most important interfaces
- Policies typically used in an OS
- Algorithms used to implement those policies

- Philosophy

- You may not ever build an OS, but
- As a CS/CE you need to understand the foundations
- Most importantly, OSs exemplify the sorts of engineering tradeoffs you'll need to make throughout your careers