

Memory Management



Today

- Basic memory management
- Swapping
- Kernel memory allocation

Next Time

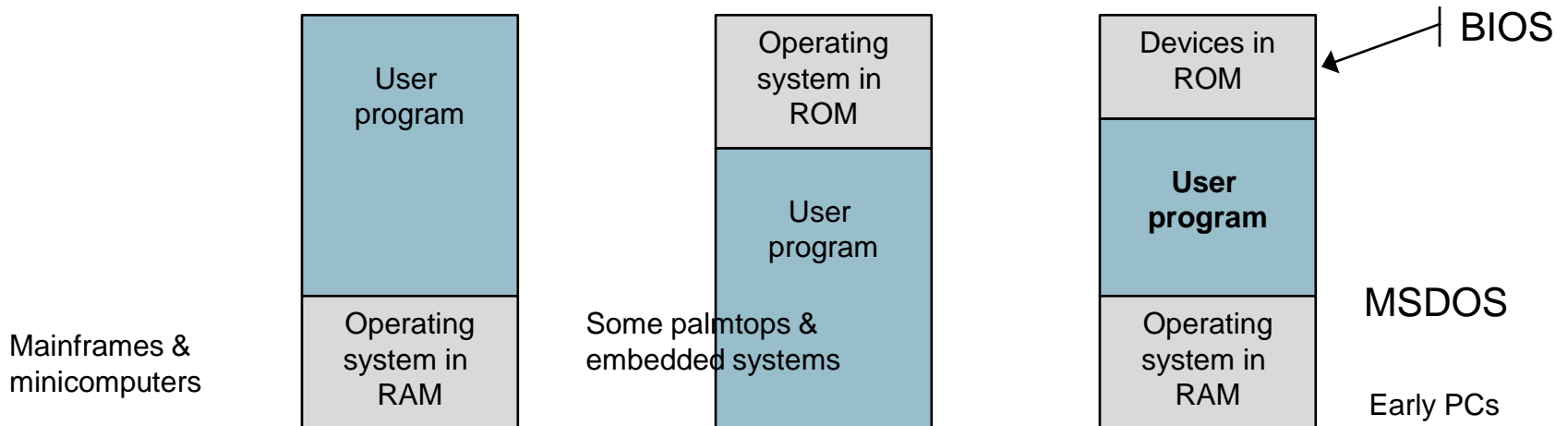
- Virtual memory

Memory management

- Ideal memory for a programmer
 - Large
 - Fast
 - Non volatile
 - Cheap
- Nothing like that → memory hierarchy
 - Small amount of fast, expensive memory – cache
 - Some medium-speed, medium price main memory
 - Gigabytes of slow, cheap disk storage
- Memory manager handles the memory hierarchy

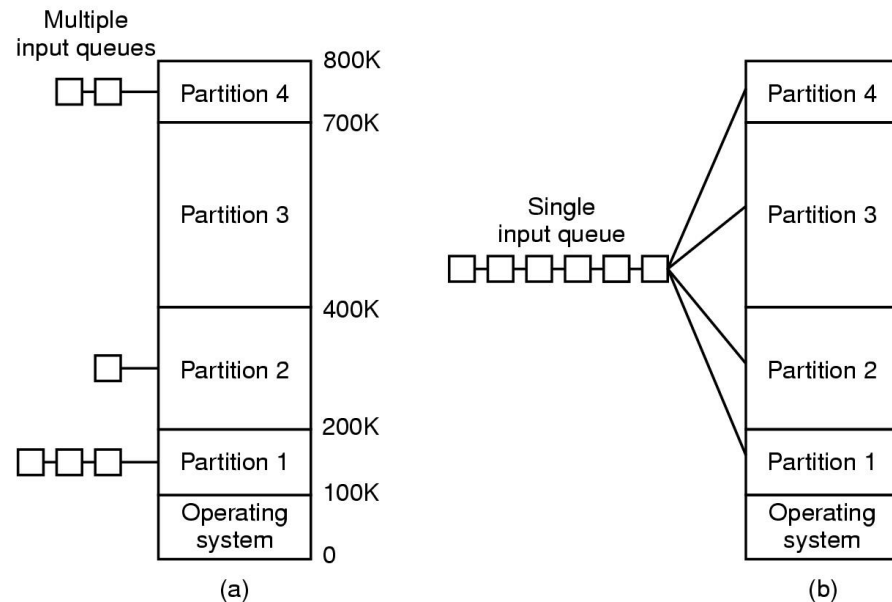
Basic memory management

- Simplest memory abstraction – no abstraction at all
 - Early mainframes (before '60), minicomputers (before '70) and PCs (before '80)
 - `MOV REG1, 1000` moves content of physical memory 1000 to register 1
 - Logically, only one program running at a time *Why?*
 - Still here, some alternatives for organizing memory



Multiprogramming w/ fixed partitions

- With a bit of hardware – Multiprogramming – while one process waits for I/O, another one can use the CPU
- Two simple approaches
 - Split memory in n parts (possible != sizes)
 - Single or separate input queues for each partition
 - ~IBM OS/360 – MFT: Multiprogramming with Fixed number of Tasks

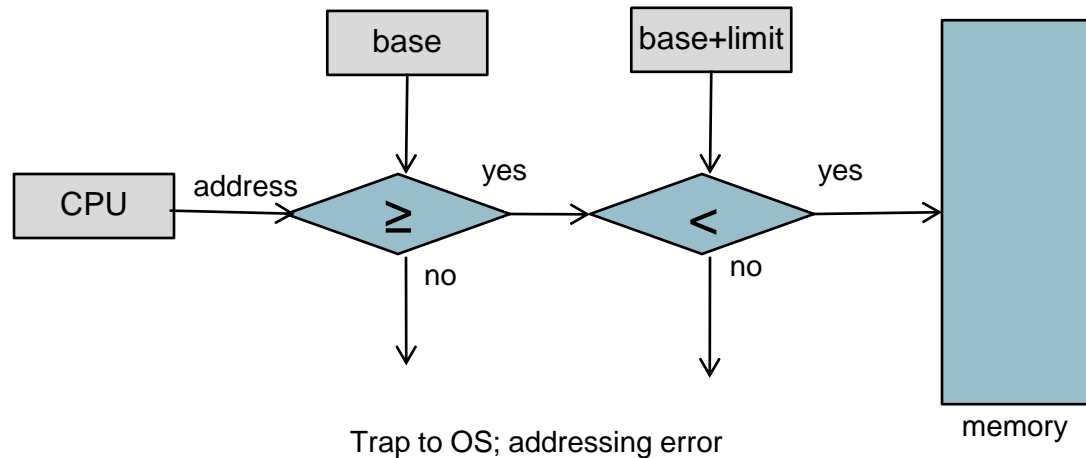


Two problems w/ multiprocessing

- Protection and relocation
 - Keep a process out of other processes' partitions
 - IBM OS/MFT - modify instructions on the fly
 - Split memory into 2KB blocks
 - Add key/code combination (4 bit)
 - The PSW kept the key
 - Don't know where a program will be loaded in memory
 - Address locations of variables & code routines
 - IBM 360 – modify program at loading time (static relocation)
- A new abstraction: Address space
 - Address space – the set of addresses a process can use to address memory
 - Each process has its own address space
- Other examples of address spaces
 - Phones, IP addresses, .com Internet domains

Two problems w/ multiprogramming

- Use base and limit values (CDC 6600 & Intel 8088)
 - Address locations + base value → physical address
 - Ideally, the base and limit registers can only be modified by the OS
 - A disadvantage – Comparisons can be done fast but additions can be expensive

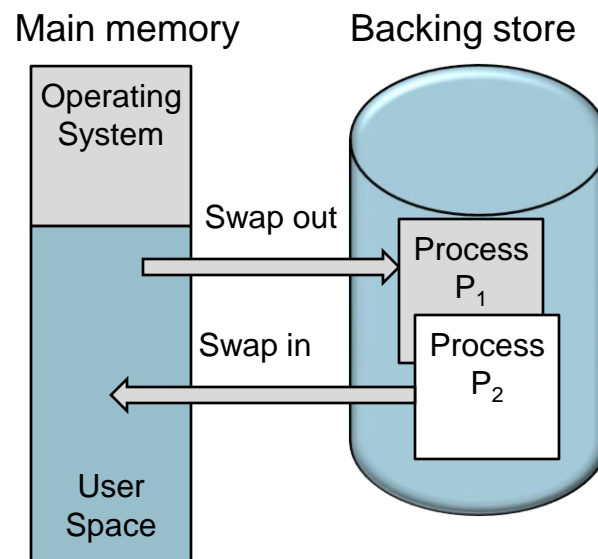


Swapping

- Not enough memory for all processes?

- Swapping

- Simplest
- Bring each process entirely
- Move another one to disk
- Compatible Time Sharing System (CTSS) – a uniprogrammed swapping system

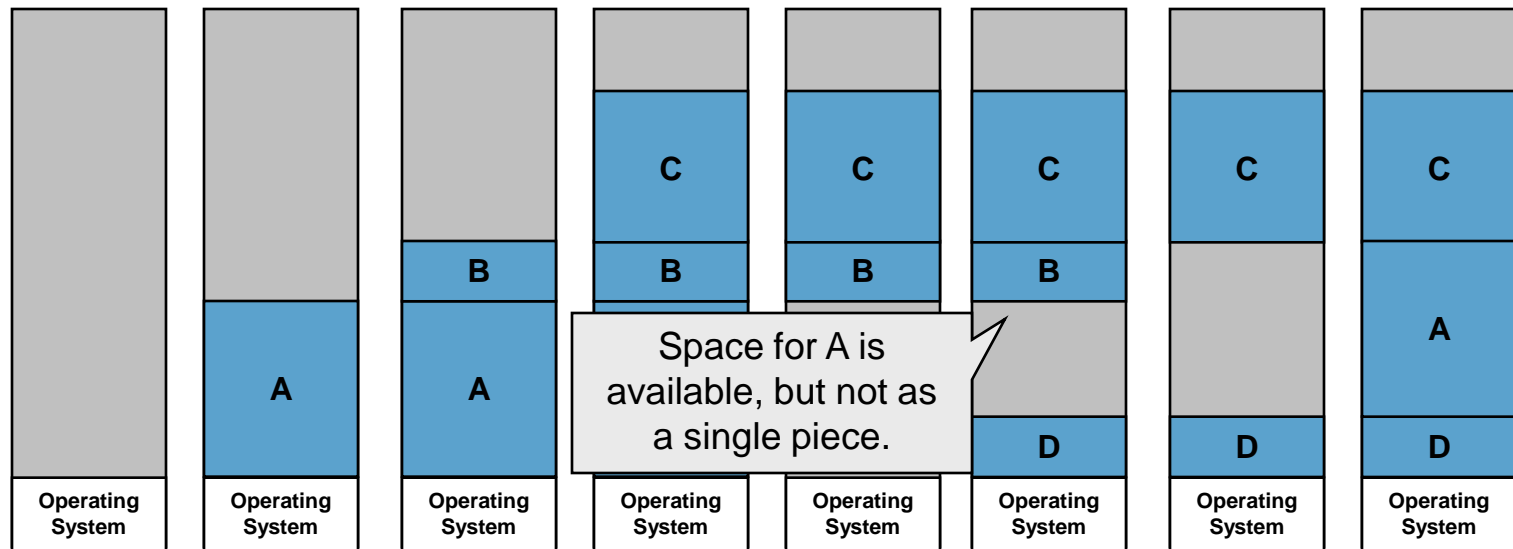


- Virtual memory (your other option)

- Allow processes to be only partially in main memory

Swapping

- How is different from MFT?
 - Much more flexible
 - Size & number of partitions changes dynamically
 - Higher memory utilization, but harder memory management
- Swapping in/out creates multiple holes
 - Fragmentation ...

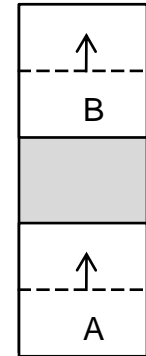


Fragmentation

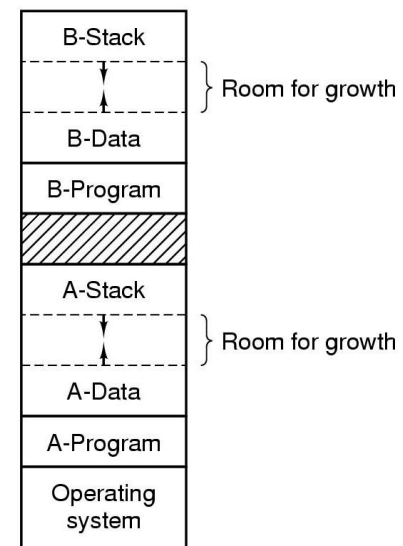
- External Fragmentation – total memory space exists to satisfy a request, but it is not contiguous
- Reduce external fragmentation by compaction
 - Shuffle contents to group free memory as one block
 - Possible only if relocation is dynamic; done at execution time
 - I/O problem
 - Latch job in memory while it is involved in I/O
 - Do I/O only into OS buffers
- Too expensive (1GB machine that can copy at 4B/20nsec will take 5 sec to compact memory!)

How much memory to allocate?

- If process' memory doesn't grow – easy
- In real world, memory needs change dynamically:
 - Swapping to make space?
 - Allocate more space to start with
 - Internal Fragmentation – leftover memory is internal to a partition
 - Remember what you used when swapping

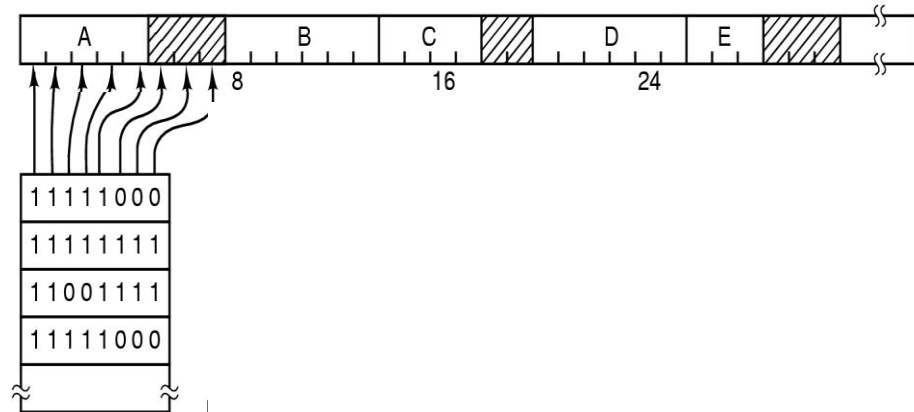


- More than one growing area per processes
 - Stack & data segment
 - If need more, same as before



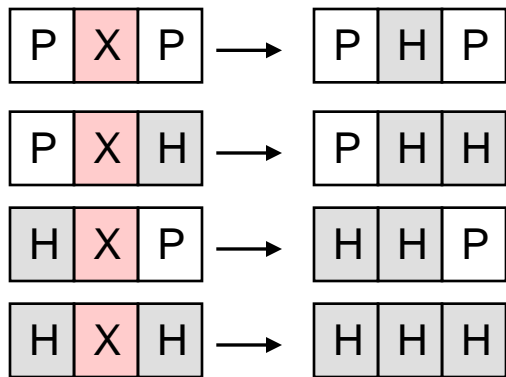
Memory management

- With dynamically allocated memory
 - OS must keep track of allocated/free memory
 - Two general approaches - bit maps and linked lists
- Bit maps
 - Divide memory into allocation units
 - For each unit, a bit in the bitmap
 - Design issues - Size of allocation unit
 - The smaller the size, the larger the bitmap
 - The larger the size, the bigger the waste
 - Simple, but slow
 - find a big enough chunk?

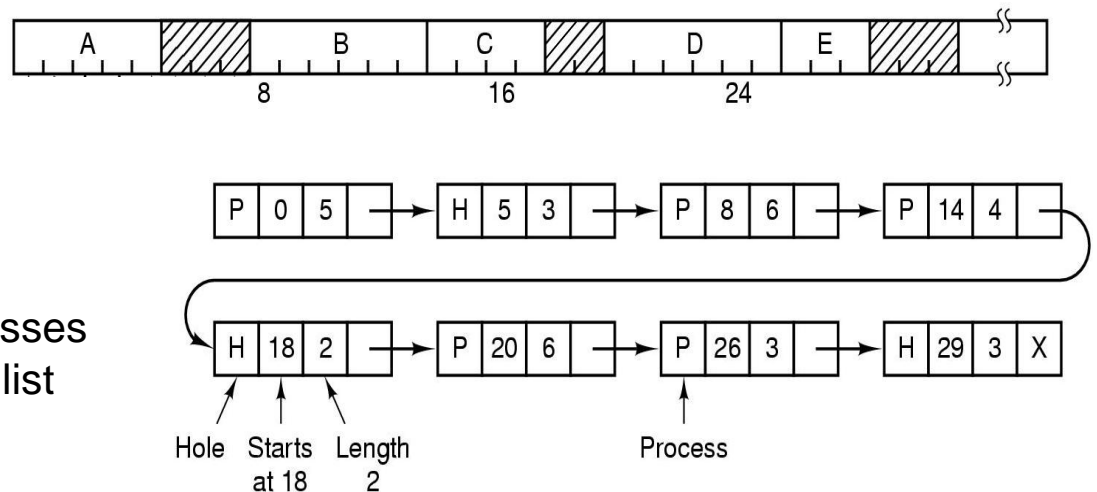


Memory management with lists

- Linked list of allocated/free space
- List ordered by address
- Double link will make your life easier
 - Updating when a process is swapped out or terminates



Keeping track of processes and holes in the same list

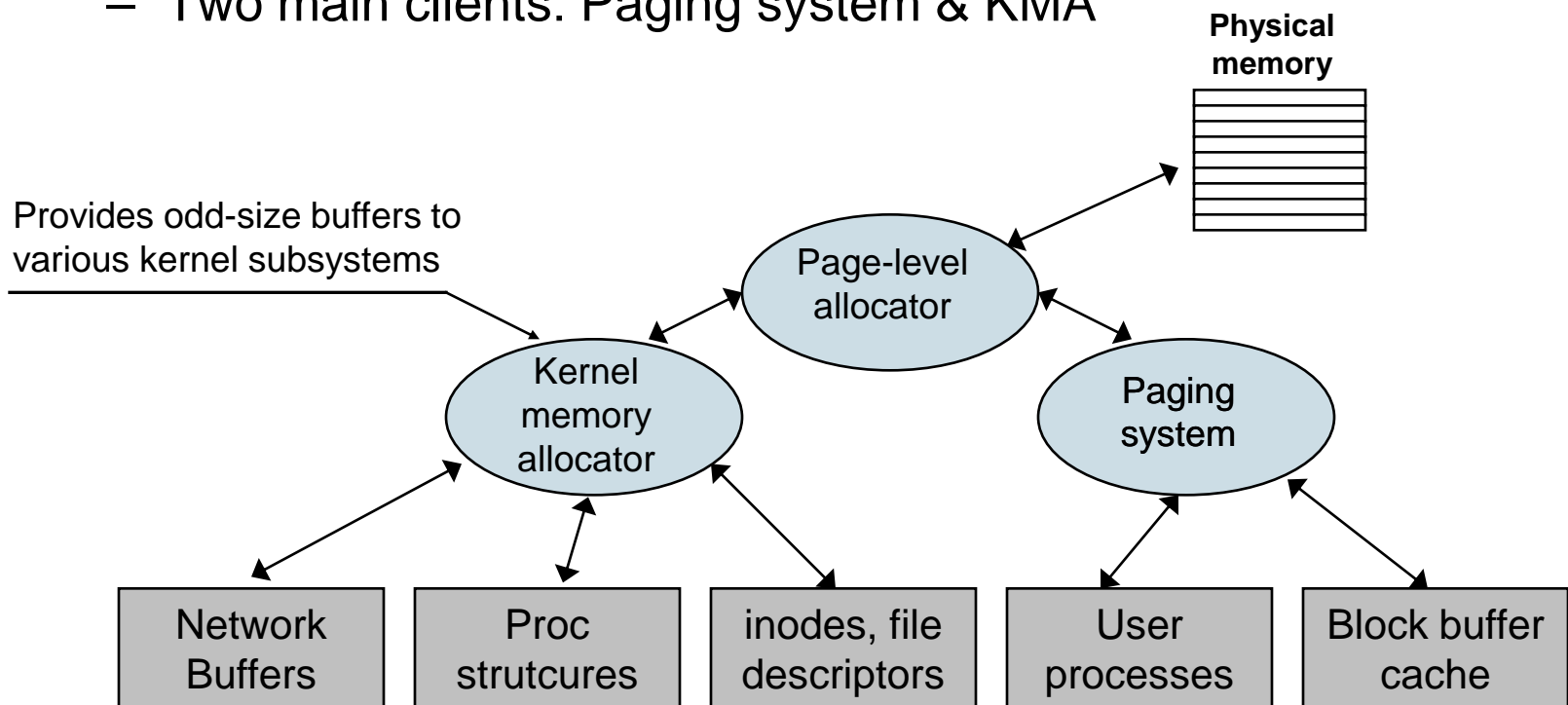


Picking a place – different algorithms

- If list of processes & holes is ordered by addresses, different ways to get memory for a new processes ...
 - First fit – simple and fast
 - Next fit - ~ First fit but start where it left off
 - Slightly worst performance than First fit
 - Best fit – try to waste the least but ...
 - More wasted in tiny holes!
 - Worst fit – try to “waste” the most (easier to reuse)
 - Not too good either
 - Speeding things up
 - Two lists (free and allocated) – slows down deallocation
 - Order the hole list – first fit ~ best fit
 - Use the same holes to keep the list
 - Quick fit – list of commonly used hole sizes
 - N lists for N different common sizes (4KB, 8KB, ...)
 - Allocation is quick, merging is expensive

Kernel memory allocation

- Most OS manage memory as set of fixed-size pages
- Kernel maintains a list of free pages
- Page-level allocator has
 - Two main routines: e.g `get_page()` & `freepage()` in SVR4
 - Two main clients: Paging system & KMA



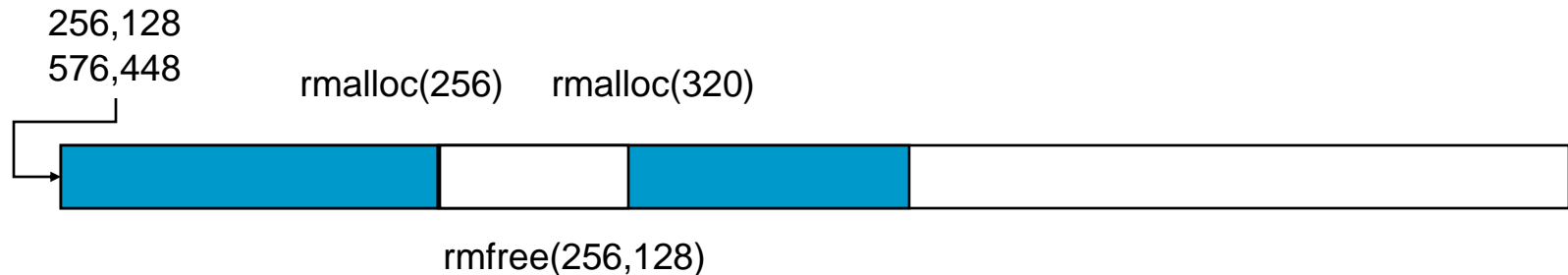
Kernel memory allocation

- KMA's common users
 - The pathname translation routine
 - Proc structures, vnodes, file descriptor blocks, ...
- Since requests \ll page \rightarrow page-level allocator is inappropriate
- KMA & the page-level allocator
 - Pre-allocates part of memory for the KMA
 - Allow KMA to request memory
 - Allow two-way exchange with the paging system
- Evaluation criteria
 - Utilization memory – physical memory is limited after all
 - Speed – it is used by various kernel subsystems
 - Simple API
 - Allow a two-way exchange with page-level allocator

KMA – Resource map allocator

- Resource map – a set of <base, size> pairs
- Initially the pool is described by a single pair
- ... after a few exchanges ... a list of entries per contiguous free regions
- Allocate requests based on
 - First fit, Best fit, Worst fit
- A simple interface

```
offset_t rmalloc(size);  
void rmfree(base, size);
```



Resource map allocator

- Pros

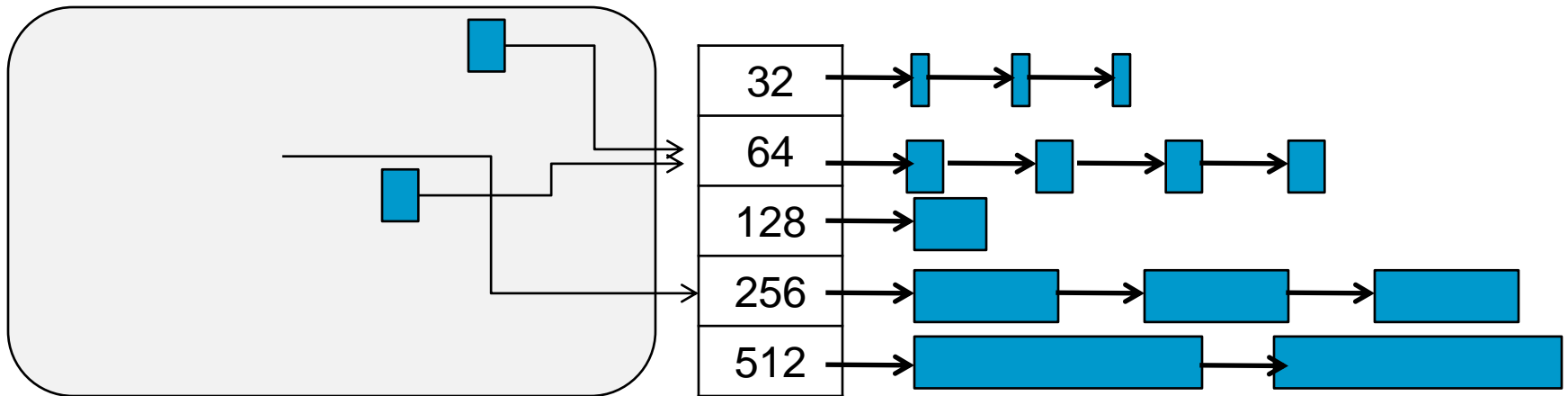
- Easy to implement
- Not restricted to memory allocation
- It avoid waste (although normally rounds up requests sizes for simplicity)
- Client can release any part of the region
- Allocator coalesces adjacent free regions

- Cons

- After a while maps ended up fragmented – low utilization
- Higher fragmentation, longer map
- Map may need an allocator for its own entries
 - *How would you implement it?*
- To coalesce regions, keep map sorted – expensive
- Linear search to find a free region large enough

KMA – Simple power-of-two free list

- A set of free lists
- Each list keeps free buffers of a particular size (2^x)
- Each buffer has one word header
 - Pointer to next free buffer, if free or to
 - Pointer to free list (or size), if allocated



KMA – Simple power-of-two free list

- Allocating(size)
 - allocating (size + header) rounded up to next power of two
 - Return pointer to first byte *after* header
- Freeing doesn't require size as argument
 - Move pointer back header-size to access header
 - Put buffer in list
- Initialize allocator by preallocating buffers or get pages on demand; if it needs a buffer from an empty list ...
 - Block request until a buffer is released
 - Satisfy request with a bigger buffer if available
 - Get a new page from page allocator

Power-of-two free lists

- Pros
 - Simple and pretty fast (avoids linear search)
 - Familiar programming interface (malloc, free)
 - Free does not require size; easier to program with
- Cons
 - Rounding means internal fragmentation
 - As many requests are power of two and we lose header; a lot of waste
 - No way to coalesce free buffers to get a bigger one
 - Rounding up may be a costly operation

Coming up ...

- The nitty-gritty details of virtual memory ...
- But first, this time for real, the midterm!