

# Machine-Level Prog. IV - Structured Data

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## Today

- Arrays
- Structures
- Unions

## Next time

- Buffer overflow, x86-64

# Basic data types

- Integral

- Stored & operated on in general registers
- Signed vs. unsigned depends on instructions used

| Intel       | GAS | Bytes | C                |
|-------------|-----|-------|------------------|
| byte        | b   | 1     | [unsigned] char  |
| word        | w   | 2     | [unsigned] short |
| double word | l   | 4     | [unsigned] int   |

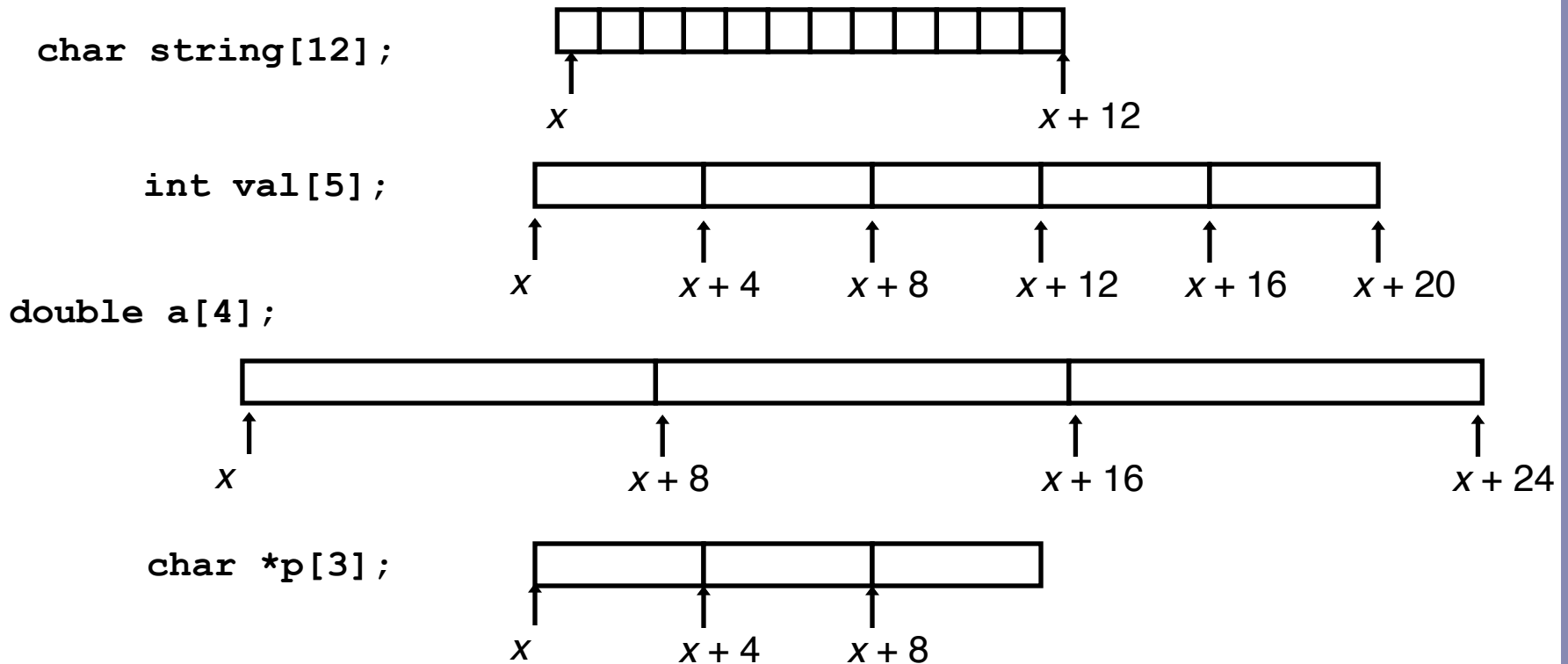
- Floating point

- Stored & operated on in floating point registers

| Intel    | GAS | Bytes | C           |
|----------|-----|-------|-------------|
| Single   | s   | 4     | float       |
| Double   | l   | 8     | double      |
| Extended | t   | 10/12 | long double |

# Array allocation

- $T$  A[L];
  - Array of data type  $T$  and length  $L$
  - Contiguously allocated region of  $L * \text{sizeof}(T)$  bytes

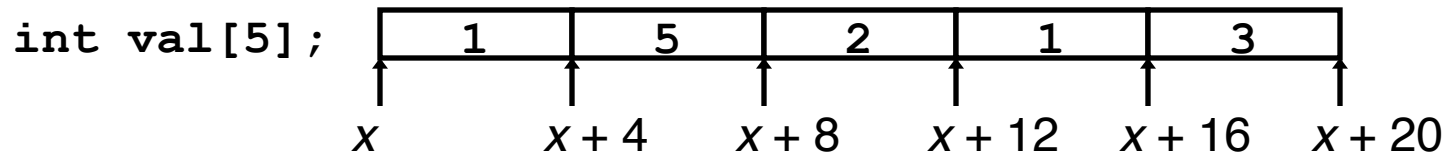


# Array access

- Basic principle

$T$   $A[L]$ ;

– Identifier  $A$  can be used as a pointer to array element 0

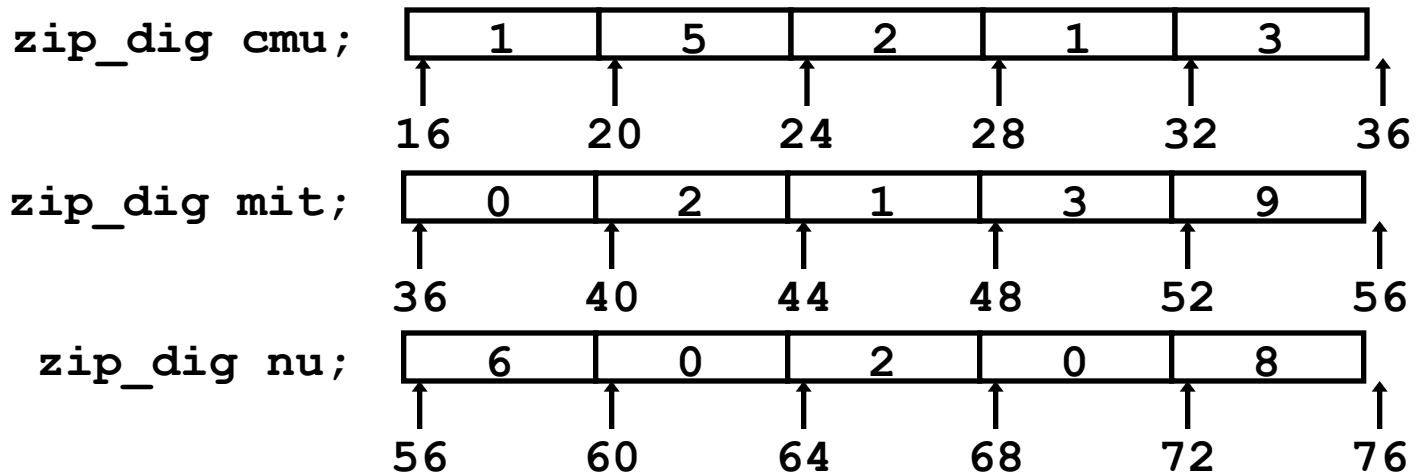


- Reference

|                          | Type               | Value     |
|--------------------------|--------------------|-----------|
| <code>val[4]</code>      | <code>int</code>   | 3         |
| <code>val</code>         | <code>int *</code> | $x$       |
| <code>val+1</code>       | <code>int *</code> | $x + 4$   |
| <code>&amp;val[2]</code> | <code>int *</code> | $x + 8$   |
| <code>val[5]</code>      | <code>int</code>   | ??        |
| <code>*(val+1)</code>    | <code>int</code>   | 5         |
| <code>val + i</code>     | <code>int *</code> | $x + 4 i$ |

# Array example

```
typedef int zip_dig[5];  
  
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig nu = { 6, 0, 2, 0, 8 };
```



- Notes

- Declaration “zip\_dig nu” equivalent to “int nu[5]”
- Example arrays were allocated in successive 20 byte blocks
  - Not guaranteed to happen in general

# Array accessing example

- Computation

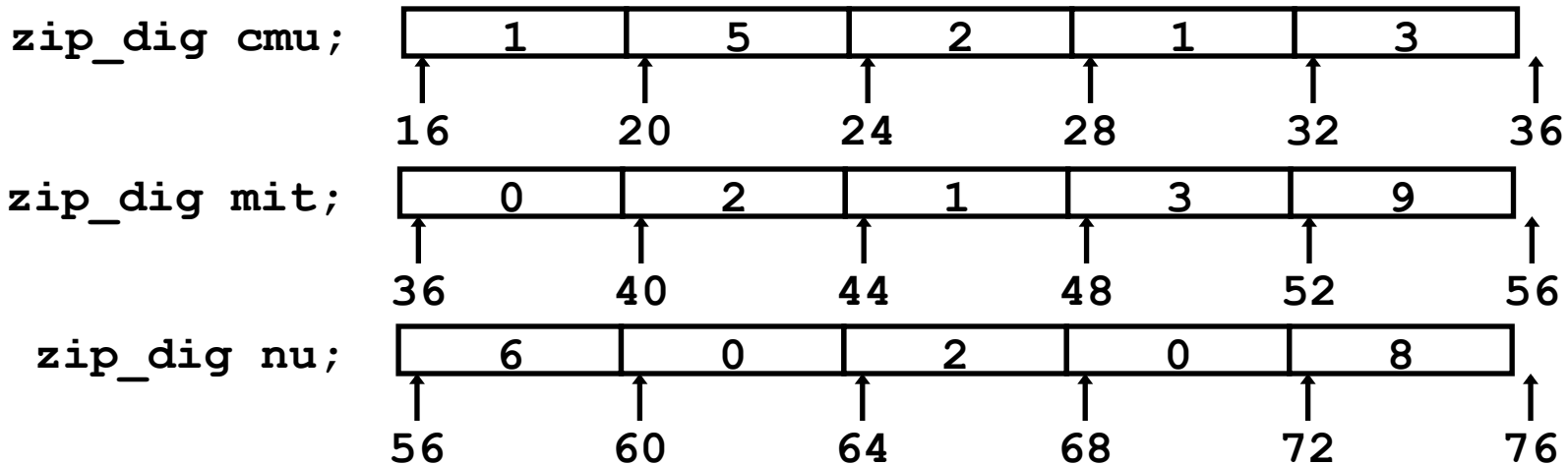
- Register `%edx` contains starting address of array
- Register `%eax` contains array index
- Desired digit at `%edx + %eax * 4`
- Use memory reference (`%edx, %eax, 4`)

```
int  
get_digit(zip_dig z,int dig)  
{  
    return z[dig];  
}
```

## Memory reference code

```
# %edx = z  
# %eax = dig  
movl (%edx,%eax,4),%eax # z[dig]
```

# Referencing examples



- Code does not do any bounds checking!

| Reference            | Address            | Value | Guaranteed? |
|----------------------|--------------------|-------|-------------|
| <code>mit[3]</code>  | $36 + 4 * 3 = 48$  | 3     | <b>Yes</b>  |
| <code>mit[5]</code>  | $36 + 4 * 5 = 56$  | 6     | <b>No</b>   |
| <code>mit[-1]</code> | $36 + 4 * -1 = 32$ | 3     | <b>No</b>   |
| <code>cmu[15]</code> | $16 + 4 * 15 = 76$ | ??    | <b>No</b>   |

- Out of range behavior implementation-dependent
  - No guaranteed relative allocation of different arrays

# Array loop example

- Original Source

Computes the integer represented by an array of 5 decimal digits.

```
int zd2int(zip_dig z)
{
    int i;
    int zi = 0;
    for (i = 0; i < 5; i++) {
        zi = 10 * zi + z[i];
    }
    return zi;
}
```

- Transformed version

As generated by GCC

- Eliminate loop variable `i` and uses pointer arithmetic
- Computes address of final element and uses that for test
- Express in do-while form
  - No need to test at entrance

```
int zd2int(zip_dig z)
{
    int zi = 0;
    int *zend = z + 4;
    do {
        zi = 10 * zi + *z;
        z++;
    } while(z <= zend);
    return zi;
}
```



# Array loop implementation

- Registers

`%ecx` `z`  
`%eax` `zi`  
`%ebx` `zend`

- Computations

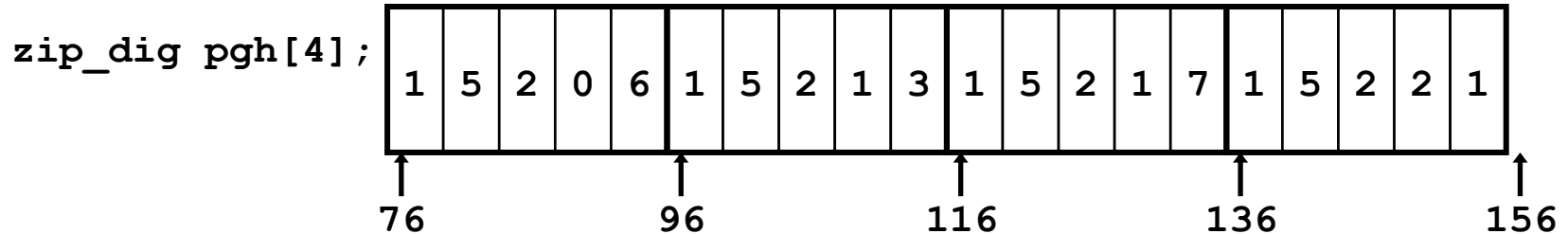
- $10 * z_i + *z$  implemented as  $*z + 2 * (z_{i+4} * z_i)$
- `z++` increments by 4

```
int zd2int(zip_dig z)
{
    int zi = 0;
    int *zend = z + 4;
    do {
        zi = 10 * zi + *z;
        z++;
    } while(z <= zend);
    return zi;
}
```

```
# %ecx = z
xorl %eax,%eax           # zi = 0
leal 16(%ecx),%ebx       # zend = z+4
.L59:
leal (%eax,%eax,4),%edx  # 5*zi
movl (%ecx),%eax        # *z
addl $4,%ecx           # z++
leal (%eax,%edx,2),%eax  # zi = *z + 2*(5*zi)
cmpl %ebx,%ecx         # z : zend
jle .L59              # if <= goto loop
```

# Nested array example

```
#define PCOUNT 4
zip_dig pgh[PCOUNT] =
  {{1, 5, 2, 0, 6},
   {1, 5, 2, 1, 3},
   {1, 5, 2, 1, 7},
   {1, 5, 2, 2, 1}};
```



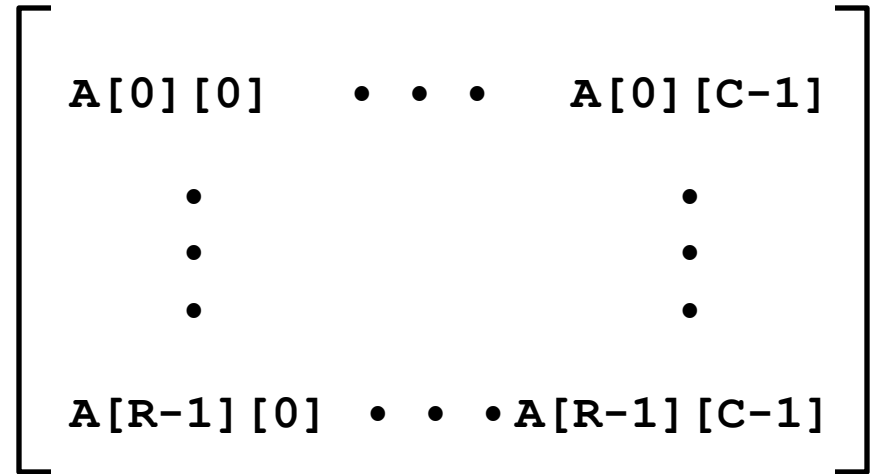
- Declaration “zip\_dig pgh[4]” equivalent to “int pgh[4][5]”
  - Variable pgh denotes array of 4 elements
    - Allocated contiguously
  - Each element is an array of 5 int’s
    - Allocated contiguously
  - “Row-Major” ordering of all elements guaranteed

# Nested array allocation

- Declaration

$T A[R][C];$

- Array of data type  $T$
- $R$  rows,  $C$  columns
- Type  $T$  element requires  $K$  bytes

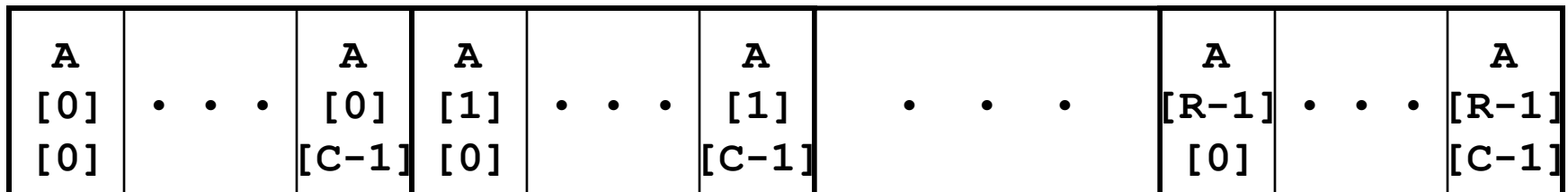


- Array size

- $R * C * K$  bytes

- Arrangement

- Row-Major Ordering `int A[R][C];`



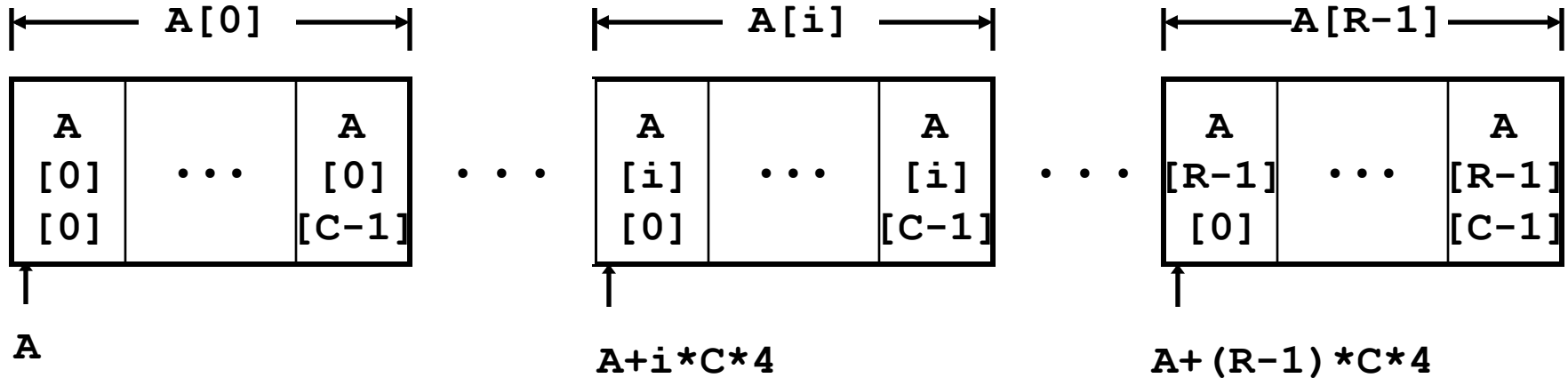
← 4 \* R \* C Bytes →

# Nested array row access

- Row vectors

- $A[i]$  is array of  $C$  elements
- Each element of type  $T$
- Starting address  $A + i * C * K$  ( $sizeof(T) = K$ )

```
int A[R][C];
```



# Nested array row access code

```
int *get_pgh_zip(int index)
{
    return pgh[index];
}
```

- Row vector
  - `pgh[index]` is array of 5 int's
  - Starting address `pgh+20*index`
- Code
  - Computes and returns address
  - Compute as `pgh + 4*(index+4*index)`

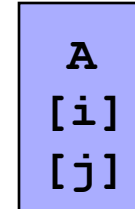
```
# %eax = index
leal (%eax,%eax,4),%eax      # 5 * index
leal pgh(,%eax,4),%eax      # pgh + (20 * index)
```

# Nested array element access

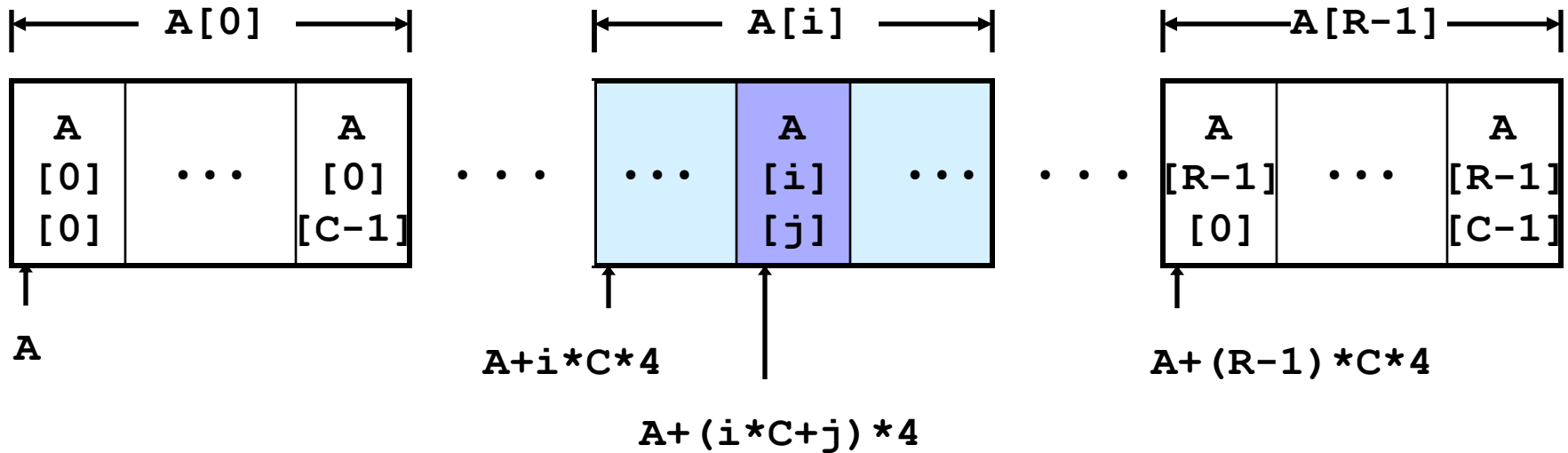
- Array elements

- $A[i][j]$  is element of type  $T$

- Address  $A + (i * C + j) * K$



```
int A[R][C];
```



# Nested array element access code

- Array Elements

- `pgh[index][dig]` is int

- Address:

- $pgh + 4 * (5 * index + dig) =$

- $pgh + 20 * index + 4 * dig$

```
int get_pgh_digit
(int index, int dig)
{
    return pgh[index][dig];
}
```

- Code

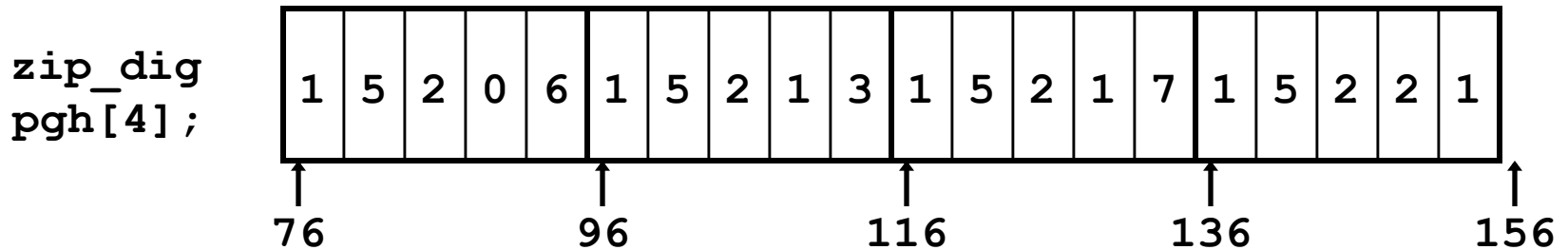
- Computes address

- $pgh + 4 * dig + 4 * (index + 4 * index)$

- `movl` performs memory reference

```
# %ecx = dig
# %eax = index
leal 0(,%ecx,4),%edx          # 4*dig
leal (%eax,%eax,4),%eax      # 5*index
movl pgh(%edx,%eax,4),%eax   # *(pgh + 4*dig + 20*index)
```

# Strange referencing examples



| Reference               | Address              | Value | Guaranteed? |
|-------------------------|----------------------|-------|-------------|
| <code>pgh[3][3]</code>  | $76+20*3+4*3 = 148$  | 2     | <b>Yes</b>  |
| <code>pgh[2][5]</code>  | $76+20*2+4*5 = 136$  | 1     | <b>Yes</b>  |
| <code>pgh[2][-1]</code> | $76+20*2+4*-1 = 112$ | 3     | <b>Yes</b>  |
| <code>pgh[4][-1]</code> | $76+20*4+4*-1 = 152$ | 1     | <b>Yes</b>  |
| <code>pgh[0][19]</code> | $76+20*0+4*19 = 152$ | 1     | <b>Yes</b>  |
| <code>pgh[0][-1]</code> | $76+20*0+4*-1 = 72$  | ??    | <b>No</b>   |

- Code does not do any bounds checking
- Ordering of elements within array guaranteed

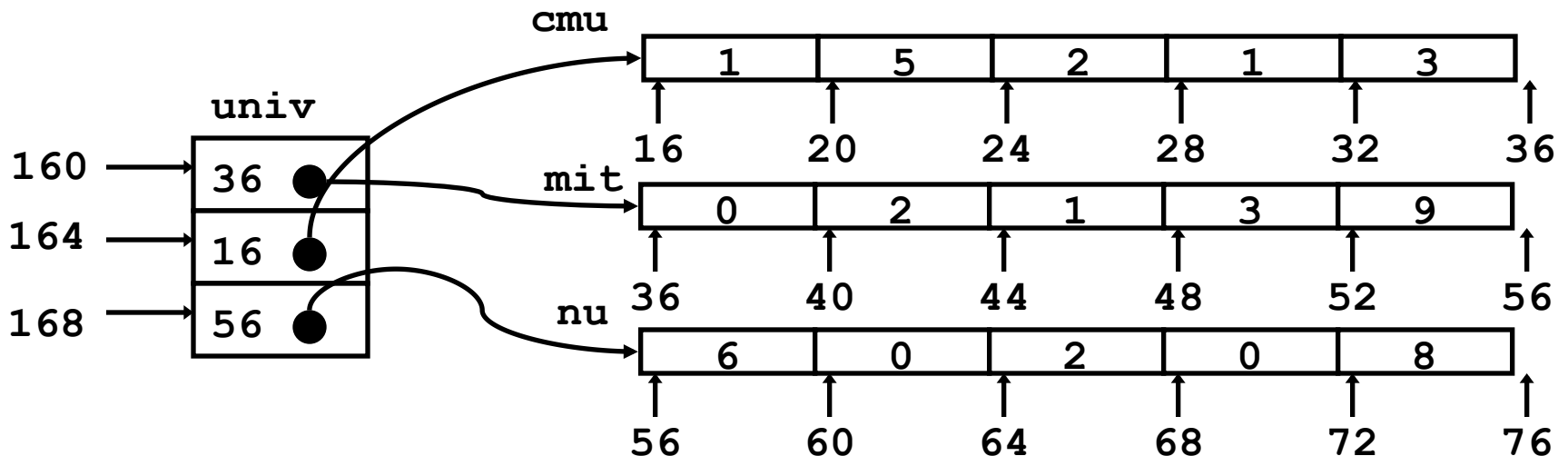


# Multi-level array example

- Variable `univ` denotes array of 3 elements
- Each element is a pointer
  - 4 bytes
- Each pointer points to array of `int`'s

```
zip_dig cmu = { 1, 5, 2, 1, 3 };  
zip_dig mit = { 0, 2, 1, 3, 9 };  
zip_dig nu  = { 6, 0, 2, 0, 8 };
```

```
#define UCOUNT 3  
int *univ[UCOUNT] = {mit, cmu, nu};
```



# Element access in multi-level array

```
int get_univ_digit
(int index, int dig)
{
    return univ[index][dig];
}
```

- Computation

- Element access  $\text{Mem}[\text{Mem}[\text{univ}+4*\text{index}]+4*\text{dig}]$
- Must do two memory reads
  - First get pointer to row array
  - Then access element within array

```
# %ecx = index
# %eax = dig
leal 0(,%ecx,4),%edx      # 4*index
movl univ(%edx),%edx      # Mem[univ+4*index]
movl (%edx,%eax,4),%eax   # Mem[...+4*dig]
```

# Array element accesses

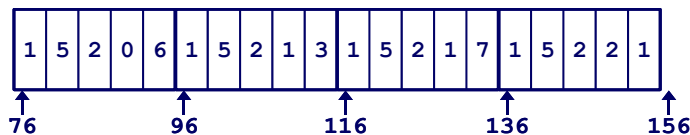
Similar C references

- Nested Array

```
int get_pgh_digit
(int index, int dig)
{
    return pgh[index][dig];
}
```

- Element at

Mem[pgh+20\*index+  
4\*dig]



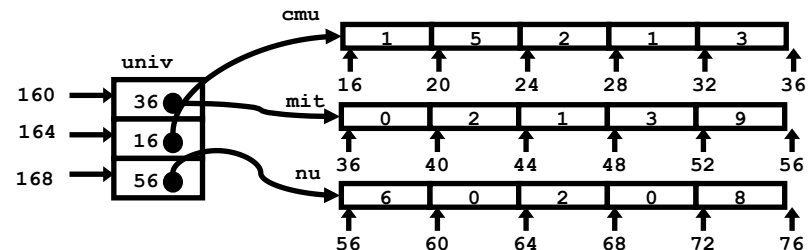
Different address computation

- Multi-Level Array

```
int get_univ_digit
(int index, int dig)
{
    return univ[index][dig];
}
```

- Element at

Mem[Mem[univ+4\*index]  
+4\*dig]



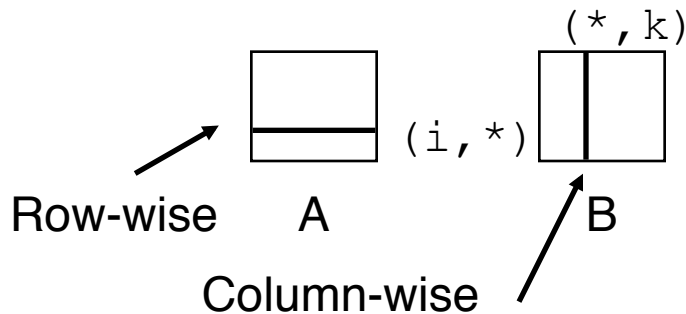
# Using nested arrays

- Strengths
  - C compiler handles doubly subscripted arrays
  - Generates very efficient code
    - Avoids multiply in index computation
- Limitation
  - Only works if have fixed array size

```
#define N 16
typedef int fix_matrix[N][N];
```

```
/* Compute element i,k of
   fixed matrix product */
int fix_prod_ele(fix_matrix a,
                 fix_matrix b,
                 int i, int k)
{
    int j;
    int result = 0;
    for (j = 0; j < N; j++)
        result += a[i][j]*b[j][k];

    return result;
}
```



# Dynamic nested arrays

- Strength
  - Can create matrix of arbitrary size
- Programming
  - Must do index computation explicitly
- Performance
  - Accessing single element costly
  - Must do multiplication

```
int *new_var_matrix(int n)
{
    return (int *)
        calloc(sizeof(int), n*n);
}
```

```
int var_ele (int *a, int i,
            int j, int n)
{
    return a[i*n+j];
}
```

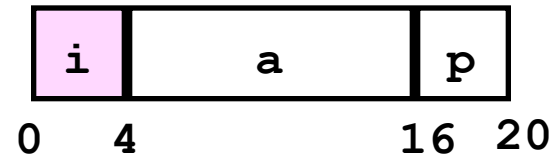
```
movl 12(%ebp),%eax    # i
movl 8(%ebp),%edx     # a
imull 20(%ebp),%eax   # n*i
addl 16(%ebp),%eax    # n*i+j
movl (%edx,%eax,4),%eax # Mem[a+4*(i*n+j)]
```

# Structures

- Concept
  - Members may be of different types
  - Contiguously-allocated region of memory
  - Refer to members within structure by names

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```

## Memory Layout



- Accessing structure member

```
void  
set_i(struct rec *r, int val)  
{  
    r->i = val; /* Same as (*r).i */  
}
```

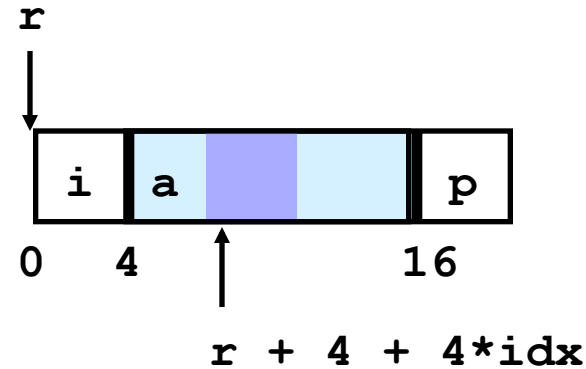
## Assembly

```
# %eax = val  
# %edx = r  
movl %eax, (%edx) # Mem[r] = val
```

Since the offset of i is 0,  
the address of r->i is r

# Generating pointer to struct. member

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```



- Generating pointer to array element
  - Offset of each structure member determined at compile time

```
int *  
find_a  
(struct rec *r, int idx)  
{  
    return &r->a[idx];  
}
```

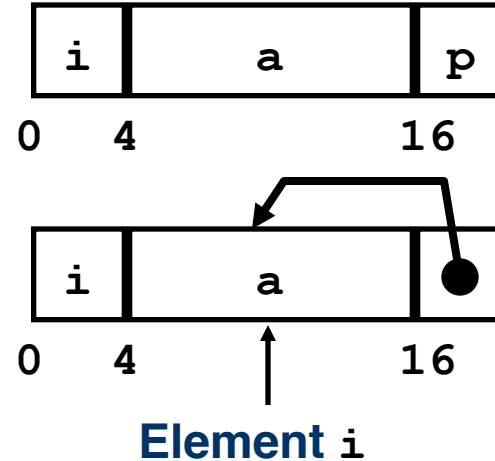
```
# %ecx = idx  
# %edx = r  
leal 0(,%ecx,4),%eax # 4*idx  
leal 4(%eax,%edx),%eax # r+4*idx+4
```

# Structure referencing (Cont.)

- C Code

```
struct rec {  
    int i;  
    int a[3];  
    int *p;  
};
```

```
void  
set_p(struct rec *r)  
{  
    r->p =  
        &r->a[r->i];  
}
```



```
# %edx = r  
movl (%edx), %ecx          # r->i  
leal 0(, %ecx, 4), %eax    # 4*(r->i)  
leal 4(%edx, %eax), %eax   # r+4+4*(r->i)  
movl %eax, 16(%edx)       # Update r->p
```



# Alignment

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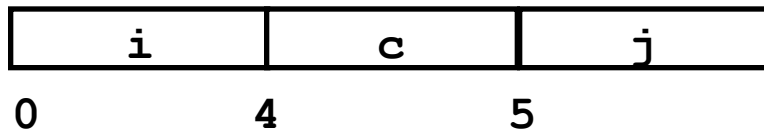
- Aligned data
  - Primitive data type requires K bytes
  - Address must be multiple of K (typically 2,4 or 8)
  - Required on some machines; advised on IA32
    - treated differently by Linux and Windows!
- Motivation for aligning data
  - Memory accessed by (aligned) double or quad-words
    - Inefficient to load or store datum that spans quad word boundaries
    - Virtual memory very tricky when datum spans 2 pages
- Compiler
  - Inserts gaps in structure to ensure correct alignment of fields

# Satisfying alignment with structures

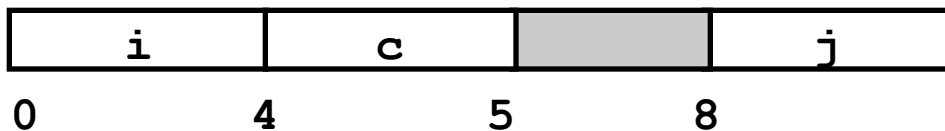
- Offsets within structure
  - Must satisfy element's alignment requirement
- Overall structure placement
  - Each structure has alignment requirement K
    - Largest alignment of any element
  - Initial address & structure length must be multiples of K

```
struct S1 {  
    int i;  
    char c;  
    int j;  
} *p;
```

- Example



Impossible to satisfy 4-byte alignment requirement for both i and j



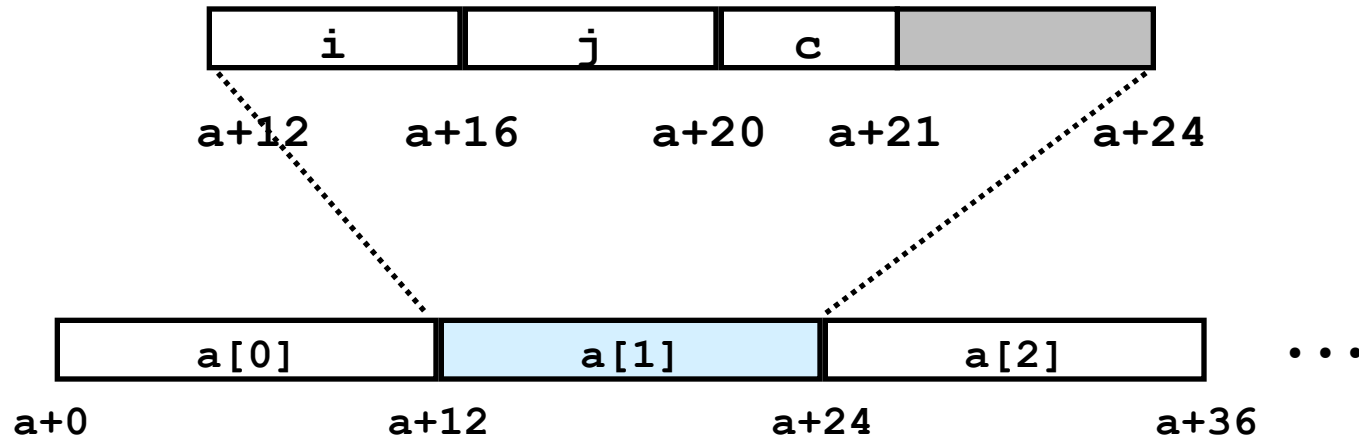
Compiler inserts a 3-byte gap to solve this

# Arrays of structures

- Principle

- Allocated by repeating allocation for array type
- In general, may nest arrays & structures to arbitrary depth
- Compiler may need to add padding to ensure each element satisfies its alignment requirements

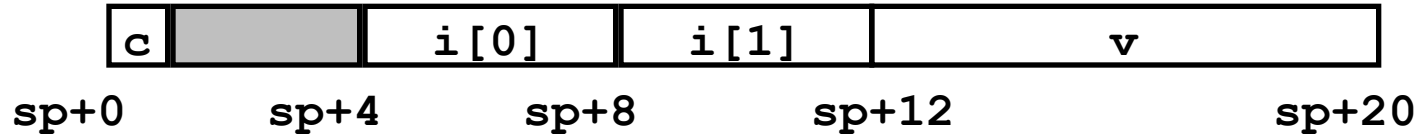
```
struct S2 {  
    int i;  
    int j;  
    char c;  
} a[4];
```



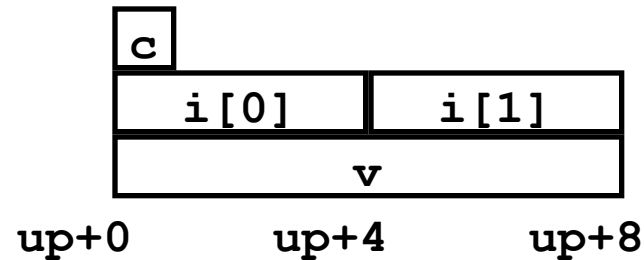
# Union allocation

- Principles
  - Overlay union elements
  - Allocate according to largest element
  - Can only use one field at a time

```
struct S1 {  
    char c;  
    int i[2];  
    double v;  
} *sp;
```

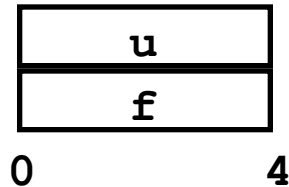


```
union U1 {  
    char c;  
    int i[2];  
    double v;  
} *up;
```



# Using union to access bit patterns

```
unsigned copy (unsigned u) {  
    return u;  
}
```



```
unsigned float2bit(float f) {  
    union {  
        float f;  
        unsigned u;  
    } temp;  
    temp.f = f;  
    return temp.u;  
}
```

- Store it using one type & access it with another one
- Get direct access to bit representation of float
- `float2bit` generates bit pattern from float
  - Same code as the one generated for `copy`
  - NOT the same as `(unsigned) f`

There's no type info in assembly code!

```
pushl    %ebp  
movl     %esp, %ebp  
movl     8(%ebp), %eax  
popl     %ebp  
ret
```

# Summary

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- Arrays in C
  - Contiguous allocation of memory
  - Pointer to first element
  - No bounds checking
- Compiler optimizations
  - Compiler often turns array code into pointer code
  - Uses addressing modes to scale array indices
  - Lots of tricks to improve array indexing in loops
- Structures
  - Allocate bytes in order declared
  - Pad in middle and at end to satisfy alignment
- Unions
  - Overlay declarations
  - Way to circumvent type system